

Numerical Stochastic Integrations and Limit Theorems

Yanghui Liu

Baruch College, CUNY

CBMS Conference, August 2-6, 2021, UAH.

A joint work with Z. Selk and S. Tindel.

Outline

- 1 Elements of rough paths
- 2 Numerical methods for rough integrals
- 3 Numerical methods for stochastic rough integrals

Presentation Outline

- 1 Elements of rough paths
- 2 Numerical methods for rough integrals
- 3 Numerical methods for stochastic rough integrals

Signatures

Signatures

- We recall some elements of rough paths.

Signatures

- We recall some elements of rough paths.
- Consider a \mathbb{R}^d -valued smooth path

$$x = (x^1, \dots, x^d).$$

Signatures

- We recall some elements of rough paths.
- Consider a \mathbb{R}^d -valued smooth path

$$x = (x^1, \dots, x^d).$$

- Consider multiple integrals of x :

$$\mathbf{x}_{st}^1 := \int_s^t dx_u = x_t - x_s \quad \mathbf{x}_{st}^2 := \int_s^t \int_s^u dx_v \otimes dx_u$$

$$\mathbf{x}_{st}^3 := \int_s^t \int_s^u \int_s^v dx_w \otimes dx_v \otimes dx_u$$

and similar definition for m-th order multiple integral \mathbf{x}^m .

Signatures

- We recall some elements of rough paths.
- Consider a \mathbb{R}^d -valued smooth path

$$x = (x^1, \dots, x^d).$$

- Consider multiple integrals of x :

$$\mathbf{x}_{st}^1 := \int_s^t dx_u = x_t - x_s \quad \mathbf{x}_{st}^2 := \int_s^t \int_s^u dx_v \otimes dx_u$$

$$\mathbf{x}_{st}^3 := \int_s^t \int_s^u \int_s^v dx_w \otimes dx_v \otimes dx_u$$

and similar definition for m -th order multiple integral \mathbf{x}^m .

- The n -th order **signature** of x :

$$S_n(x)_{st} = (\mathbf{x}_{st}^1, \mathbf{x}_{st}^2, \dots, \mathbf{x}_{st}^n).$$

It is known that for fixed s and t , the $S_n(x)_{st}$ contains all information of x for $n = \infty$.

Rough paths

Rough paths

- Consider p -variation continuous path x in \mathbb{R}^d . We denote $\delta x_{st} = x_t - x_s$.

Rough paths

- Consider p -variation continuous path x in \mathbb{R}^d . We denote $\delta x_{st} = x_t - x_s$.
- Recall that the p -variation norm is defined as

$$\|x\|_{p\text{-var}} = \left(\sup_{(t_k) \in \mathcal{P}} \sum_k |\delta x_{t_k t_{k+1}}|^p \right)^{1/p},$$

where \mathcal{P} is the set of finite partitions of the time interval $[0, T]$.

Rough paths

- Consider p -variation continuous path x in \mathbb{R}^d . We denote $\delta x_{st} = x_t - x_s$.
- Recall that the p -variation norm is defined as

$$\|x\|_{p\text{-var}} = \left(\sup_{(t_k) \in \mathcal{P}} \sum_k |\delta x_{t_k t_{k+1}}|^p \right)^{1/p},$$

where \mathcal{P} is the set of finite partitions of the time interval $[0, T]$.

- Denote x^ε : a mollification of x .

Rough paths

- Consider p -variation continuous path x in \mathbb{R}^d . We denote $\delta x_{st} = x_t - x_s$.
- Recall that the p -variation norm is defined as

$$\|x\|_{p\text{-var}} = \left(\sup_{(t_k) \in \mathcal{P}} \sum_k |\delta x_{t_k t_{k+1}}|^p \right)^{1/p},$$

where \mathcal{P} is the set of finite partitions of the time interval $[0, T]$.

- Denote x^ϵ : a mollification of x .
- Suppose that for $n = \lfloor p \rfloor$ the n th order signature $S_n(x^\epsilon)$ of x^ϵ converges under the p -variation norm and denote the limit by $S_n(x) := \mathbf{x}$. Then \mathbf{x} is called a p -rough path.

Itô map

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

- $S_n(x)$: signature of x .

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

- $S_n(x)$: signature of x .
- $S_n(y)$: signature of solution y .

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

- $S_n(x)$: signature of x .
- $S_n(y)$: signature of solution y .
- Consider the Itô map $I : S_n(x) \rightarrow S_n(y)$.

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

- $S_n(x)$: signature of x .
- $S_n(y)$: signature of solution y .
- Consider the Itô map $I : S_n(x) \rightarrow S_n(y)$.
- I is **continuous** under p -var norm with $p < n + 1$. (Lyons '98)

Itô map

- Consider differential equation for a smooth function x :

$$y_t = y_0 + \int_0^t V(y_u) dx_u, \quad t \in [0, T].$$

- $S_n(x)$: signature of x .
- $S_n(y)$: signature of solution y .
- Consider the Itô map $I : S_n(x) \rightarrow S_n(y)$.
- I is **continuous** under p -var norm with $p < n + 1$. (Lyons '98)
- We extend the Itô map I to p -variation rough paths. We define $\mathbf{y} = I(\mathbf{x})$ as the solution of the differential equation

$$d\mathbf{y}_t = V(y_t) d\mathbf{x}_t.$$

Applications

Applications

- The rough paths theory provides a framework for differential equations driven by an **arbitrary irregular** noise.

Applications

- The rough paths theory provides a framework for differential equations driven by an **arbitrary irregular** noise.
- Such solutions are **path-wise** solutions. No probability structure is required (e.g. Markovian or martingale).

Applications

- The rough paths theory provides a framework for differential equations driven by an **arbitrary irregular** noise.
- Such solutions are **path-wise** solutions. No probability structure is required (e.g. Markovian or martingale).
- The rough paths framework provides the stability of the Itô map.

Applications

- The rough paths theory provides a framework for differential equations driven by an **arbitrary irregular** noise.
- Such solutions are **path-wise** solutions. No probability structure is required (e.g. Markovian or martingale).
- The rough paths framework provides the stability of the Itô map.
- The signature has been applied to model complex data streams.

Presentation Outline

- 1 Elements of rough paths
- 2 Numerical methods for rough integrals**
- 3 Numerical methods for stochastic rough integrals

Rough integrations

Rough integrations

- Consider a p -rough path x . Denote x^ϵ : a mollification of x .

Rough integrations

- Consider a p -rough path x . Denote x^ϵ : a mollification of x .
- For $V \in C^\infty$ we define the rough integral:

$$\int_0^T V(x) dx = \lim_{\epsilon \rightarrow 0} \int_0^T V(x^\epsilon) dx^\epsilon.$$

Rough integrations

- Consider a p -rough path x . Denote x^ϵ : a mollification of x .
- For $V \in C^\infty$ we define the rough integral:

$$\int_0^T V(x) dx = \lim_{\epsilon \rightarrow 0} \int_0^T V(x^\epsilon) dx^\epsilon.$$

- Let (t_k) be a partition of $[0, T]$. For each k we consider the approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} V(x_{t_k}) dx_t = V(x_{t_k}) \delta x_{t_k t_{k+1}}.$$

Rough integrations

- Consider a p -rough path x . Denote x^ϵ : a mollification of x .
- For $V \in C^\infty$ we define the rough integral:

$$\int_0^T V(x) dx = \lim_{\epsilon \rightarrow 0} \int_0^T V(x^\epsilon) dx^\epsilon.$$

- Let (t_k) be a partition of $[0, T]$. For each k we consider the approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} V(x_{t_k}) dx_t = V(x_{t_k}) \delta x_{t_k t_{k+1}}.$$

- This leads to the Riemann sum approximation

$$\int_0^T V(x_t) dx_t = \sum_k \int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \sum_k V(x_{t_k}) \delta x_{t_k t_{k+1}}.$$

Rough integrations

- Consider a p -rough path x . Denote x^ϵ : a mollification of x .
- For $V \in C^\infty$ we define the rough integral:

$$\int_0^T V(x) dx = \lim_{\epsilon \rightarrow 0} \int_0^T V(x^\epsilon) dx^\epsilon.$$

- Let (t_k) be a partition of $[0, T]$. For each k we consider the approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} V(x_{t_k}) dx_t = V(x_{t_k}) \delta x_{t_k t_{k+1}}.$$

- This leads to the Riemann sum approximation

$$\int_0^T V(x_t) dx_t = \sum_k \int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \sum_k V(x_{t_k}) \delta x_{t_k t_{k+1}}.$$

- Note that if $p \geq 2$ the Riemann sum $\sum_k V(x_{t_k}) \delta x_{t_k t_{k+1}}$ **diverges**.

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx$$

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} \underbrace{\left(V(x_{t_k}) + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^1 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^{n-1} \right)}_{\text{The first } n \text{ terms of Taylor expansion of } V(y_t) \text{ at } t} dx_t$$

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} \underbrace{\left(V(x_{t_k}) + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^1 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^{n-1} \right)}_{\text{The first } n \text{ terms of Taylor expansion of } V(y_t) \text{ at } t} dx_t$$

$$= V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n$$

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} \underbrace{\left(V(x_{t_k}) + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^1 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^{n-1} \right)}_{\text{The first } n \text{ terms of Taylor expansion of } V(y_t) \text{ at } t} dx_t$$

$$= V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n$$

- We obtain the **compensated Riemann sum**:

$$\int_0^T V(x_t) dx_t \approx \sum_k V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n.$$

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} \underbrace{\left(V(x_{t_k}) + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^1 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^{n-1} \right)}_{\text{The first } n \text{ terms of Taylor expansion of } V(y_t) \text{ at } t} dx_t$$

$$= V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n$$

- We obtain the **compensated Riemann sum**:

$$\int_0^T V(x_t) dx_t \approx \sum_k V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n.$$

- The compensated Riemann sum converges to the rough integral $\int_0^T V(x) dx$ when $n > p - 1$.

- Denote $\mathcal{L}V = \partial VV$ and $\mathcal{L}^n = \mathcal{L} \circ \dots \circ \mathcal{L}$.
- We consider an improved approximation

$$\int_{t_k}^{t_{k+1}} V(x_t) dx_t \approx \int_{t_k}^{t_{k+1}} \underbrace{\left(V(x_{t_k}) + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^1 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^{n-1} \right)}_{\text{The first } n \text{ terms of Taylor expansion of } V(y_t) \text{ at } t} dx_t$$

$$= V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n$$

- We obtain the **compensated Riemann sum**:

$$\int_0^T V(x_t) dx_t \approx \sum_k V(x_{t_k})\delta x_{t_k t_{k+1}} + (\mathcal{L}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^2 + \dots + (\mathcal{L}^{n-1}V)(x_{t_k})\mathbf{x}_{t_k t_{k+1}}^n.$$

- The compensated Riemann sum converges to the rough integral $\int_0^T V(x) dx$ when $n > p - 1$.
- Note that the compensated Riemann sum requires the computations of signatures of x .

Multi-dimensional rough integral

Multi-dimensional rough integral

- Rough integration with respect to random fields have been studied in the following cases:
 - 2-dim Young integral: **Towghi '01** and **Quer-Sardanyons-Tindel '07**
 - 2-dim rough integral of order $> 1/3$: **Chouk-Gubinelli '18**
 - Multi-dim Young integral: **Harang '18**

Multi-dimensional rough integral

- Rough integration with respect to random fields have been studied in the following cases:
 - 2-dim Young integral: **Towghi '01** and **Quer-Sardanyons-Tindel '07**
 - 2-dim rough integral of order $> 1/3$: **Chouk-Gubinelli '18**
 - Multi-dim Young integral: **Harang '18**
- Let x and y be 2d Hölder functions on $[0, T]^2$ of order (α_1, α_2) and (β_1, β_2) , respectively, and $\alpha_i + \beta_i > 1$, $i = 1, 2$. The Riemann sum

$$\sum_{(t_i), (t'_j)} y_{t_i t'_j} x_{t'_i t'_{j+1}}^{t_i t_{i+1}}$$

converges to the Young integral $\int_{[0, T]^2} y_{st} dx_{st}$.

Multi-dimensional rough integral

- Rough integration with respect to random fields have been studied in the following cases:
 - 2-dim Young integral: **Towghi '01** and **Quer-Sardanyons-Tindel '07**
 - 2-dim rough integral of order $> 1/3$: **Chouk-Gubinelli '18**
 - Multi-dim Young integral: **Harang '18**
- Let x and y be 2d Hölder functions on $[0, T]^2$ of order (α_1, α_2) and (β_1, β_2) , respectively, and $\alpha_i + \beta_i > 1$, $i = 1, 2$. The Riemann sum

$$\sum_{(t_i), (t'_j)} y_{t_i t'_j} x_{t'_i t'_{i+1}}^{t_i t_{i+1}}$$

converges to the Young integral $\int_{[0, T]^2} y_{st} dx_{st}$.

- The Riemann sum is divergent when $\alpha_i + \beta_i < 1$, $i = 1$ or 2 , and compensated Riemann sum is introduced.

Presentation Outline

- 1 Elements of rough paths
- 2 Numerical methods for rough integrals
- 3 Numerical methods for stochastic rough integrals**

- Let $X = (X^1, \dots, X^d)$ be a continuous centered Gaussian process with i.i.d. components.

- Let $X = (X^1, \dots, X^d)$ be a continuous centered Gaussian process with i.i.d. components.
- The covariance function of X is defined as follows

$$R(s, t) = \mathbb{E}[X_s^j X_t^j].$$

- Let $X = (X^1, \dots, X^d)$ be a continuous centered Gaussian process with i.i.d. components.
- The covariance function of X is defined as follows

$$R(s, t) = \mathbb{E}[X_s^j X_t^j].$$

- The information concerning X is mostly encoded in the rectangular increments of R :

$$R_{uv}^{st} := R(t, v) - R(t, u) - R(s, v) + R(s, u) = \mathbb{E}[\delta X_{st}^j \delta X_{uv}^j].$$

- Let $X = (X^1, \dots, X^d)$ be a continuous centered Gaussian process with i.i.d. components.
- The covariance function of X is defined as follows

$$R(s, t) = \mathbb{E}[X_s^j X_t^j].$$

- The information concerning X is mostly encoded in the rectangular increments of R :

$$R_{uv}^{st} := R(t, v) - R(t, u) - R(s, v) + R(s, u) = \mathbb{E}[\delta X_{st}^j \delta X_{uv}^j].$$

- For $\rho \geq 1$ we define the ρ -variation of R as

$$\|R\|_{\rho\text{-var}} = \sup_{(t_i), (t'_j)} \left(\sum_{i,j} |R_{t_i t_{i+1}}^{t'_j t'_{j+1}}|^\rho \right)^{1/\rho},$$

where (t_j) and (t'_j) are partitions on $[0, T]$.

- Let $X = (X^1, \dots, X^d)$ be a continuous centered Gaussian process with i.i.d. components.
- The covariance function of X is defined as follows

$$R(s, t) = \mathbb{E}[X_s^j X_t^j].$$

- The information concerning X is mostly encoded in the rectangular increments of R :

$$R_{uv}^{st} := R(t, v) - R(t, u) - R(s, v) + R(s, u) = \mathbb{E}[\delta X_{st}^j \delta X_{uv}^j].$$

- For $\rho \geq 1$ we define the ρ -variation of R as

$$\|R\|_{\rho\text{-var}} = \sup_{(t_j), (t'_j)} \left(\sum_{i,j} |R_{t_i t_{i+1}}^{t'_j t'_{j+1}}|^\rho \right)^{1/\rho},$$

where (t_j) and (t'_j) are partitions on $[0, T]$.

- If R has finite ρ -variation for $\rho \in [1, 2)$, then X gives rise to a ρ -rough path, provided $\rho > 2\rho$. (Friz-Victoir '11).

- Consider a process y such that

$$\delta y_{st} = y'_s \mathbf{X}_{st}^1 + y''_s \mathbf{X}_{st}^2 + r_{st}^0, \quad \delta y'_{st} = y''_s \mathbf{X}_{st}^1 + r_{st}^1,$$

where y' , y'' , r^0 , r^1 are processes satisfying some regularity conditions.

- Consider a process y such that

$$\delta y_{st} = y'_s \mathbf{X}_{st}^1 + y''_s \mathbf{X}_{st}^2 + r_{st}^0, \quad \delta y'_{st} = y''_s \mathbf{X}_{st}^1 + r_{st}^1,$$

where y' , y'' , r^0 , r^1 are processes satisfying some regularity conditions.

- y is called a controlled paths of X of order 2. Such processes contains most of the interesting examples. e.g. $y = V(X)$ or y is the solution of a RDE.

Define the trapezoid rule:

$$\text{tr-}\mathcal{J}_0^T(y, X) = \sum_k \frac{y_{t_k} + y_{t_{k+1}}}{2} \cdot \delta X_{t_k t_{k+1}}.$$

Define the trapezoid rule:

$$\text{tr-}\mathcal{J}_0^T(y, X) = \sum_k \frac{y_{t_k} + y_{t_{k+1}}}{2} \cdot \delta X_{t_k t_{k+1}}.$$

Theorem (Liu-Selk-Tindel '21)

Define the trapezoid rule:

$$\text{tr-}\mathcal{J}_0^T(y, X) = \sum_k \frac{y_{t_k} + y_{t_{k+1}}}{2} \cdot \delta X_{t_k t_{k+1}}.$$

Theorem (Liu-Selk-Tindel '21)

- Suppose that $\|R\|_{\rho\text{-var}} < \infty$. Then as the mesh size of the partition (t_k) goes to 0 we have

$$\text{tr-}\mathcal{J}_0^T(y, X) \rightarrow \int_0^T y_t d\mathbf{X}_t \quad \text{in probability.}$$

Define the trapezoid rule:

$$\text{tr-}\mathcal{J}_0^T(y, X) = \sum_k \frac{y_{t_k} + y_{t_{k+1}}}{2} \cdot \delta X_{t_k t_{k+1}}.$$

Theorem (Liu-Selk-Tindel '21)

- Suppose that $\|R\|_{\rho\text{-var}} < \infty$. Then as the mesh size of the partition (t_k) goes to 0 we have

$$\text{tr-}\mathcal{J}_0^T(y, X) \rightarrow \int_0^T y_t d\mathbf{X}_t \quad \text{in probability.}$$

- Suppose that there exists a constant $C > 0$ such that $\|R\|_{\rho\text{-var}; [s,t] \times [0,T]} \leq C|t - s|$ for all $[s, t] \subset [0, T]$. Then we have

$$\text{tr-}\mathcal{J}_0^T(y, X) \rightarrow \int_0^T y_t d\mathbf{X}_t \quad \text{almost surely.}$$

Ingredients of proof.

Ingredients of proof.

With a careful rearrangement of the trapezoid rule one can recast it as

$$\text{tr- } \mathcal{J}_0^T(y, X) = \sum_k l_1 + l_2 + l_3 + l_4,$$

Ingredients of proof.

With a careful rearrangement of the trapezoid rule one can recast it as

$$\text{tr- } \mathcal{J}_0^T(y, X) = \sum_k l_1 + l_2 + l_3 + l_4,$$

where

$$l_1 = y_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^1 + y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2 + y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_2 = \frac{1}{2} y'_{t_k} \mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2$$

$$l_3 = \frac{1}{2} y''_{t_k} \mathbf{X}_{t_k t_{k+1}}^2 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_4 = \frac{1}{2} r_{t_k t_{k+1}}^0 \cdot \mathbf{X}_{t_k t_{k+1}}^1.$$

Ingredients of proof.

With a careful rearrangement of the trapezoid rule one can recast it as

$$\text{tr- } \mathcal{J}_0^T(y, X) = \sum_k l_1 + l_2 + l_3 + l_4,$$

where

$$l_1 = y_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^1 + y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2 + y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_2 = \frac{1}{2} y'_{t_k} \mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2$$

$$l_3 = \frac{1}{2} y''_{t_k} \mathbf{X}_{t_k t_{k+1}}^2 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_4 = \frac{1}{2} r_{t_k t_{k+1}}^0 \cdot \mathbf{X}_{t_k t_{k+1}}^1.$$

- l_1 is the compensated Riemann sum of $\int_0^T y d\mathbf{X}$.

Ingredients of proof.

With a careful rearrangement of the trapezoid rule one can recast it as

$$\text{tr- } \mathcal{J}_0^T(y, X) = \sum_k l_1 + l_2 + l_3 + l_4,$$

where

$$l_1 = y_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^1 + y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2 + y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_2 = \frac{1}{2} y'_{t_k} \mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2$$

$$l_3 = \frac{1}{2} y''_{t_k} \mathbf{X}_{t_k t_{k+1}}^2 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_4 = \frac{1}{2} r_{t_k t_{k+1}}^0 \cdot \mathbf{X}_{t_k t_{k+1}}^1.$$

- l_1 is the compensated Riemann sum of $\int_0^T y d\mathbf{X}$.
- l_2 and l_3 are weighted random sums of the forms: $\sum_k y'_{t_k} h_{t_k t_{k+1}}^n$ and $\sum_k y''_{t_k} \tilde{h}_{t_k t_{k+1}}^n$.

Ingredients of proof.

With a careful rearrangement of the trapezoid rule one can recast it as

$$\text{tr- } \mathcal{J}_0^T(y, X) = \sum_k l_1 + l_2 + l_3 + l_4,$$

where

$$l_1 = y_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^1 + y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2 + y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_2 = \frac{1}{2} y'_{t_k} \mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y'_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^2$$

$$l_3 = \frac{1}{2} y''_{t_k} \mathbf{X}_{t_k t_{k+1}}^2 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - y''_{t_k} \cdot \mathbf{X}_{t_k t_{k+1}}^3$$

$$l_4 = \frac{1}{2} r_{t_k t_{k+1}}^0 \cdot \mathbf{X}_{t_k t_{k+1}}^1.$$

- l_1 is the compensated Riemann sum of $\int_0^T y d\mathbf{X}$.
- l_2 and l_3 are weighted random sums of the forms: $\sum_k y'_{t_k} h_{t_k t_{k+1}}^n$ and $\sum_k y''_{t_k} \tilde{h}_{t_k t_{k+1}}^n$.
- The convergences of l_i , $i = 2, 3, 4$ can be shown based on a transfer principle combined with some 2d young-type estimates.

Transfer principle (Liu-Tindel '19)

Transfer principle (Liu-Tindel '19)

- In order to bound a weighted sum $\sum_{k=0}^{n-1} y_{t_k} h_{t_k t_{k+1}}^n$ it suffices to consider the following elementary weighted sums:

$$\sum_{s \leq t_k < t} h_{t_k t_{k+1}}^n, \quad \sum_{s \leq t_k < t} \mathbf{x}_{st_k}^1 h_{t_k t_{k+1}}^n, \quad \dots \quad \sum_{s \leq t_k < t} \mathbf{x}_{st_k}^\ell h_{t_k t_{k+1}}^n,$$

where ℓ is an integer depending on X and h^n .

Transfer principle (Liu-Tindel '19)

- In order to bound a weighted sum $\sum_{k=0}^{n-1} y_{t_k} h_{t_k t_{k+1}}^n$ it suffices to consider the following elementary weighted sums:

$$\sum_{s \leq t_k < t} h_{t_k t_{k+1}}^n, \quad \sum_{s \leq t_k < t} \mathbf{X}_{st_k}^1 h_{t_k t_{k+1}}^n, \quad \dots \quad \sum_{s \leq t_k < t} \mathbf{X}_{st_k}^\ell h_{t_k t_{k+1}}^n,$$

where ℓ is an integer depending on X and h^n .

- These special weighted sums belong to finite Wiener chaos and are easier to handle.

Transfer principle (Liu-Tindel '19)

- In order to bound a weighted sum $\sum_{k=0}^{n-1} y_{t_k} h_{t_k t_{k+1}}^n$ it suffices to consider the following elementary weighted sums:

$$\sum_{s \leq t_k < t} h_{t_k t_{k+1}}^n, \quad \sum_{s \leq t_k < t} \mathbf{X}_{st_k}^1 h_{t_k t_{k+1}}^n, \dots, \sum_{s \leq t_k < t} \mathbf{X}_{st_k}^\ell h_{t_k t_{k+1}}^n,$$

where ℓ is an integer depending on X and h^n .

- These special weighted sums belong to finite Wiener chaos and are easier to handle.
- For example, in order to estimate $I_2 = \frac{1}{2} \sum_k y'_{t_k} (\mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - \mathbf{X}_{t_k t_{k+1}}^2)$ it suffices to bound

$$\sum_k (\mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - \mathbf{X}_{t_k t_{k+1}}^2) \quad \text{and} \quad \sum_k \mathbf{X}_{t_k}^1 (\mathbf{X}_{t_k t_{k+1}}^1 \cdot \mathbf{X}_{t_k t_{k+1}}^1 - \mathbf{X}_{t_k t_{k+1}}^2)$$

Transfer principle (Liu-Tindel '19)

- In order to bound a weighted sum $\sum_{k=0}^{n-1} y_{t_k} h_{t_k t_{k+1}}^n$ it suffices to consider the following elementary weighted sums:

$$\sum_{s \leq t_k < t} h_{t_k t_{k+1}}^n, \quad \sum_{s \leq t_k < t} \mathbf{x}_{st_k}^1 h_{t_k t_{k+1}}^n, \dots, \sum_{s \leq t_k < t} \mathbf{x}_{st_k}^\ell h_{t_k t_{k+1}}^n,$$

where ℓ is an integer depending on X and h^n .

- These special weighted sums belong to finite Wiener chaos and are easier to handle.
- For example, in order to estimate $I_2 = \frac{1}{2} \sum_k y'_{t_k} (\mathbf{x}_{t_k t_{k+1}}^1 \cdot \mathbf{x}_{t_k t_{k+1}}^1 - \mathbf{x}_{t_k t_{k+1}}^2)$ it suffices to bound

$$\sum_k (\mathbf{x}_{t_k t_{k+1}}^1 \cdot \mathbf{x}_{t_k t_{k+1}}^1 - \mathbf{x}_{t_k t_{k+1}}^2) \quad \text{and} \quad \sum_k \mathbf{x}_{t_k}^1 (\mathbf{x}_{t_k t_{k+1}}^1 \cdot \mathbf{x}_{t_k t_{k+1}}^1 - \mathbf{x}_{t_k t_{k+1}}^2)$$

- Such transfer principle for limit theorems of weighted sums are obtained and has been applied to very general weighted sum.

Let f be a smooth function on \mathbb{R}^m . Define the midpoint rule:

$$m\text{-}\mathcal{J}_0^T(f(X), X) = \sum_{k=0}^{n-1} f\left(\frac{X_{t_k} + X_{t_{k+1}}}{2}\right) \cdot \delta X_{t_k t_{k+1}}.$$

Let f be a smooth function on \mathbb{R}^m . Define the midpoint rule:

$$m\text{-}\mathcal{J}_0^T(f(X), X) = \sum_{k=0}^{n-1} f\left(\frac{X_{t_k} + X_{t_{k+1}}}{2}\right) \cdot \delta X_{t_k t_{k+1}}.$$

Corollary

Let f be a smooth function on \mathbb{R}^m . Define the midpoint rule:

$$\text{m-}\mathcal{J}_0^T(f(X), X) = \sum_{k=0}^{n-1} f\left(\frac{X_{t_k} + X_{t_{k+1}}}{2}\right) \cdot \delta X_{t_k t_{k+1}}.$$

Corollary

- Suppose that $\|R\|_{\rho\text{-var}} < \infty$. Then as the mesh size of the partition (t_k) goes to 0 we have

$$\text{m-}\mathcal{J}_0^T(f(X), X) \rightarrow \int_0^T f(X_t) d\mathbf{X}_t \quad \text{in probability.}$$

Let f be a smooth function on \mathbb{R}^m . Define the midpoint rule:

$$m\text{-}\mathcal{J}_0^T(f(X), X) = \sum_{k=0}^{n-1} f\left(\frac{X_{t_k} + X_{t_{k+1}}}{2}\right) \cdot \delta X_{t_k t_{k+1}}.$$

Corollary

- Suppose that $\|R\|_{\rho\text{-var}} < \infty$. Then as the mesh size of the partition (t_k) goes to 0 we have

$$m\text{-}\mathcal{J}_0^T(f(X), X) \rightarrow \int_0^T f(X_t) d\mathbf{X}_t \quad \text{in probability.}$$

- If we assume further that $\|R\|_{\rho\text{-var}; [s,t] \times [0,T]} \leq C|t-s|$. Then the convergence holds almost surely.

Ingredients of proof:

For $a, b \in \mathbb{R}^d$ we consider the following mean value identity

$$\frac{f(a) + f(b)}{2} - f\left(\frac{a+b}{2}\right) = \frac{1}{2} \partial^2 f(c) \left(\frac{b-a}{2}\right)^{\otimes 2},$$

where $c \in \mathbb{R}^d$ satisfies $c = a + \theta(b - a)$ for some $\theta \in [0, 1]$.

Ingredients of proof:

For $a, b \in \mathbb{R}^d$ we consider the following mean value identity

$$\frac{f(a) + f(b)}{2} - f\left(\frac{a+b}{2}\right) = \frac{1}{2} \partial^2 f(c) \left(\frac{b-a}{2}\right)^{\otimes 2},$$

where $c \in \mathbb{R}^d$ satisfies $c = a + \theta(b - a)$ for some $\theta \in [0, 1]$.

- Apply the mean value identity with $a = X_{t_k}$ and $b = X_{t_{k+1}}$ to the difference

$$\text{tr-}\mathcal{J}_0^T(f(X), X) - \text{m-}\mathcal{J}_0^T(f(X), X).$$

We will obtain some weighted sums similar to I_3 and I_4 in the previous proof.

Ingredients of proof:

For $a, b \in \mathbb{R}^d$ we consider the following mean value identity

$$\frac{f(a) + f(b)}{2} - f\left(\frac{a+b}{2}\right) = \frac{1}{2} \partial^2 f(c) \left(\frac{b-a}{2}\right)^{\otimes 2},$$

where $c \in \mathbb{R}^d$ satisfies $c = a + \theta(b - a)$ for some $\theta \in [0, 1]$.

- Apply the mean value identity with $a = X_{t_k}$ and $b = X_{t_{k+1}}$ to the difference

$$\text{tr-}\mathcal{J}_0^T(f(X), X) - \text{m-}\mathcal{J}_0^T(f(X), X).$$

We will obtain some weighted sums similar to I_3 and I_4 in the previous proof.

- We conclude that the two numerical integral methods converge to the same limit.

Thank you very much for your attention!