

# Optimal regularity of SPDEs with additive noise

Davar Khoshnevisan

University of Utah

<http://www.math.utah.edu/~davar>

Joint work with Marta Sanz-Solé

Many thanks to the

United States' NSF & Spain's *Ministerio de Ciencia e Innovación*

## A constant-coefficient example

- Let  $\dot{W} = \dot{W}(t, x)$  denote space-time white noise on  $\mathbf{R}_+ \times \mathbf{R}$ ; that is,

## A constant-coefficient example

- Let  $\dot{W} = \dot{W}(t, x)$  denote space-time white noise on  $\mathbf{R}_+ \times \mathbf{R}$ ; that is,
- $\dot{W}$  is a centered random Gaussian distribution with correlations given somewhat formally by

$$\text{Cov}[\dot{W}(t, x), \dot{W}(s, y)] = \delta_0(t - s)\delta_0(x - y) \quad s, t \geq 0, x, y \in \mathbf{R}.$$

## A constant-coefficient example

- Let  $\dot{W} = \dot{W}(t, x)$  denote space-time white noise on  $\mathbf{R}_+ \times \mathbf{R}$ ; that is,
- $\dot{W}$  is a centered random Gaussian distribution with correlations given somewhat formally by

$$\text{Cov}[\dot{W}(t, x), \dot{W}(s, y)] = \delta_0(t - s)\delta_0(x - y) \quad s, t \geq 0, x, y \in \mathbf{R}.$$

- Consider the following linear stochastic heat equation:

$$\partial_t u(t, x) = \partial_x^2 u(t, x) + \dot{W}(t, x),$$

subject to  $u(0) = 0$

## A constant-coefficient example

- Let  $\dot{W} = \dot{W}(t, x)$  denote space-time white noise on  $\mathbf{R}_+ \times \mathbf{R}$ ; that is,
- $\dot{W}$  is a centered random Gaussian distribution with correlations given somewhat formally by

$$\text{Cov}[\dot{W}(t, x), \dot{W}(s, y)] = \delta_0(t - s)\delta_0(x - y) \quad s, t \geq 0, x, y \in \mathbf{R}.$$

- Consider the following linear stochastic heat equation:

$$\partial_t u(t, x) = \partial_x^2 u(t, x) + \dot{W}(t, x),$$

subject to  $u(0) = 0$

- The solution is of course

$$u(t, x) = \int_{(0,t) \times \mathbf{R}} p(t-s, y-x) W(ds dy),$$

where  $p(t, x) = (4\pi t)^{-1/2} \exp\{-x^2/(4t)\} = \text{heat kernel}$

# A constant-coefficient example

$$\partial_t u = \partial_x^2 u + \dot{W}$$

Theorem (Krylov-Rozovskii, 1972; Pardoux, 1972)

*u is continuous with probability one. In fact,*

$$u \in \bigcap_{\alpha < \frac{1}{2}} C_{loc}^{\alpha/2, \alpha}((0, \infty) \times \mathbf{R}) \quad a.s.$$

## A constant-coefficient example

$$\partial_t u = \partial_x^2 u + \dot{W}$$

Theorem (Krylov-Rozovskii, 1972; Pardoux, 1972)

*u is continuous with probability one. In fact,*

$$u \in \bigcap_{\alpha < \frac{1}{2}} C_{loc}^{\alpha/2, \alpha}((0, \infty) \times \mathbf{R}) \quad \text{a.s.}$$

Theorem (mentioned as aside – we will not return to this)

*With probability one:*

## A constant-coefficient example

$$\partial_t u = \partial_x^2 u + \dot{W}$$

Theorem (Krylov-Rozovskii, 1972; Pardoux, 1972)

*u is continuous with probability one. In fact,*

$$u \in \bigcap_{\alpha < \frac{1}{2}} C_{loc}^{\alpha/2, \alpha}((0, \infty) \times \mathbf{R}) \quad \text{a.s.}$$

Theorem (mentioned as aside – we will not return to this)

*With probability one:*

- (Lei-Nualart, 2009) For every  $t > 0$  fixed,  $u(t) = fBM(\frac{1}{4}) + C^\infty$ -process



## A constant-coefficient example

$$\partial_t u = \partial_x^2 u + \dot{W}$$

Theorem (Krylov-Rozovskii, 1972; Pardoux, 1972)

*u is continuous with probability one. In fact,*

$$u \in \bigcap_{\alpha < \frac{1}{2}} C_{loc}^{\alpha/2, \alpha}((0, \infty) \times \mathbf{R}) \quad \text{a.s.}$$

Theorem (mentioned as aside – we will not return to this)

*With probability one:*

- (Lei-Nualart, 2009) For every  $t > 0$  fixed,  $u(t) = fBM(\frac{1}{4}) + C^\infty$ -process
- (Foondun-K-Mahboubi, 2009) For every  $x \in \mathbf{R}$  fixed,  $u(\cdot, x) = BM + C^\infty$ -process

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F}$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\dot{F}$  = centered generalized Gaussian noise with  $[\phi_1, \phi_2 \in \mathcal{S}(\mathbf{R}^d)]$

$$\begin{aligned} & \text{Cov} \left[ \int_{(0,t) \times \mathbf{R}^d} \phi_1(x) F(ds dx), \int_{(0,s) \times \mathbf{R}^d} \phi_2(x) F(ds dx) \right] \\ &= (s \wedge t) \langle \phi_1 \phi_2 * \Gamma \rangle_{L^2(\mathbf{R}^d)} \quad s, t > 0, \end{aligned}$$

where  $\Gamma$  is a positive-definite tempered Borel measure on  $\mathbf{R}^d$

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F} \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\dot{F}$  = centered generalized Gaussian noise with  $[\phi_1, \phi_2 \in \mathcal{S}(\mathbf{R}^d)]$

$$\begin{aligned} \text{Cov} & \left[ \int_{(0,t) \times \mathbf{R}^d} \phi_1(x) F(ds dx), \int_{(0,s) \times \mathbf{R}^d} \phi_2(x) F(ds dx) \right] \\ & = (s \wedge t) \langle \phi_1 \phi_2 * \Gamma \rangle_{L^2(\mathbf{R}^d)} \quad s, t > 0, \end{aligned}$$

where  $\Gamma$  is a positive-definite tempered Borel measure on  $\mathbf{R}^d$

- Now consider the following SPDE: For  $t > 0$  and  $x \in \mathbf{R}^d$ ,

$$\partial_t u(t, x) = \Delta u(t, x) + b(u(t, x)) + \dot{F}(t, x),$$

subject to  $u(0) \in L^\infty(\mathbf{R}^d)$  being non random (say)

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F}$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\dot{F}$  = centered generalized Gaussian noise with  $[\phi_1, \phi_2 \in \mathcal{S}(\mathbf{R}^d)]$

$$\begin{aligned} & \text{Cov} \left[ \int_{(0,t) \times \mathbf{R}^d} \phi_1(x) F(ds dx), \int_{(0,s) \times \mathbf{R}^d} \phi_2(x) F(ds dx) \right] \\ &= (s \wedge t) \langle \phi_1 \phi_2 * \Gamma \rangle_{L^2(\mathbf{R}^d)} \quad s, t > 0, \end{aligned}$$

where  $\Gamma$  is a positive-definite tempered Borel measure on  $\mathbf{R}^d$

- Now consider the following SPDE: For  $t > 0$  and  $x \in \mathbf{R}^d$ ,

$$\partial_t u(t, x) = \Delta u(t, x) + b(u(t, x)) + \dot{F}(t, x),$$

subject to  $u(0) \in L^\infty(\mathbf{R}^d)$  being non random (say)

- $b : \mathbf{R} \rightarrow \mathbf{R}$  is non-random and Lipschitz continuous

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F}$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

### Theorem (Dalang, 1999)

*The SPDE has a random-field solution  $u$  if*

$$\int_{\mathbf{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \|\xi\|^2} < \infty.$$

*When  $b \equiv 0$ , this condition is necessary and sufficient.*

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F}$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

### Theorem (Dalang, 1999)

The SPDE has a random-field solution  $u$  if

$$\int_{\mathbf{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \|\xi\|^2} < \infty.$$

When  $b \equiv 0$ , this condition is necessary and sufficient.

### Theorem (Sanz-Solé–Sarra, 2000; 2002)

$u =$  Hölder continuous if there exists  $\eta \in (0, 1)$  such that

$$\int_{\mathbf{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \|\xi\|^{2\eta}} < \infty.$$

## Other SPDEs

$$\partial_t u = \Delta u + b(u) + \dot{F}$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

### Theorem (Dalang, 1999)

The SPDE has a random-field solution  $u$  if

$$\int_{\mathbf{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \|\xi\|^2} < \infty.$$

When  $b \equiv 0$ , this condition is necessary and sufficient.

### Theorem (Sanz-Solé–Sarra, 2000; 2002)

$u =$  Hölder continuous if there exists  $\eta \in (0, 1)$  such that

$$\int_{\mathbf{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \|\xi\|^{2\eta}} < \infty.$$

- Both theories also allow multiplicative-noise models

## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$



## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$
- Let  $p(t)$  denote the transition functions of  $X$ ; that is,

$$p(t, F) = P\{X_t \in F\} \quad \text{for } t > 0 \text{ and Borel sets } F \subset \mathbf{R}^d$$

## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$
- Let  $p(t)$  denote the transition functions of  $X$ ; that is,

$$p(t, F) = \mathbb{P}\{X_t \in F\} \quad \text{for } t > 0 \text{ and Borel sets } F \subset \mathbf{R}^d$$

- $p$  = the fundamental solution for  $\partial_t - \mathcal{L}$

## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$
- Let  $p(t)$  denote the transition functions of  $X$ ; that is,

$$p(t, F) = \mathbb{P}\{X_t \in F\} \quad \text{for } t > 0 \text{ and Borel sets } F \subset \mathbf{R}^d$$

- $p$  = the fundamental solution for  $\partial_t - \mathcal{L}$
- By solution we mean

$$H(t, x) = \int_{(0, t) \times \mathbf{R}^d} p(t - s, y - x) F(ds dy)$$

though with a little care since  $p$  is not always a function

## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$
- Let  $p(t)$  denote the transition functions of  $X$ ; that is,

$$p(t, F) = \mathbb{P}\{X_t \in F\} \quad \text{for } t > 0 \text{ and Borel sets } F \subset \mathbf{R}^d$$

- $p$  = the fundamental solution for  $\partial_t - \mathcal{L}$
- By solution we mean

$$H(t, x) = \int_{(0, t) \times \mathbf{R}^d} p(t - s, y - x) F(ds dy)$$

though with a little care since  $p$  is not always a function

- When does this make sense ( $\leftrightarrow$  the SPDE is well posed)?

## A heat generalization

$$\partial_t H = \mathcal{L}H + \dot{F}, \quad H(0) = 0, \quad \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$
- Let  $p(t)$  denote the transition functions of  $X$ ; that is,

$$p(t, F) = \mathbb{P}\{X_t \in F\} \quad \text{for } t > 0 \text{ and Borel sets } F \subset \mathbf{R}^d$$

- $p$  = the fundamental solution for  $\partial_t - \mathcal{L}$
- By solution we mean

$$H(t, x) = \int_{(0, t) \times \mathbf{R}^d} p(t - s, y - x) F(ds dy)$$

though with a little care since  $p$  is not always a function

- When does this make sense ( $\leftrightarrow$  the SPDE is well posed)?
- When is the solution Hölder continuous?

## A wave generalization

$$\partial_t^2 W = \mathcal{L}W + \dot{F}, \quad W(0) = 0, \quad \partial_t W(0+) = 0,$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$  with  $d = 1, 2, 3$

## A wave generalization

$$\partial_t^2 W = \mathcal{L}W + \dot{F}, \quad W(0) = 0, \quad \partial_t W(0+) = 0,$$

$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$  with  $d = 1, 2, 3$
- $\varphi$  = the fundamental solution for  $\partial_t^2 - \mathcal{L}$

## A wave generalization

$$\partial_t^2 W = \mathcal{L}W + \dot{F}, \quad W(0) = 0, \quad \partial_t W(0+) = 0, \\ \text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$  with  $d = 1, 2, 3$
- $\varphi$  = the fundamental solution for  $\partial_t^2 - \mathcal{L}$
- By solution we mean

$$W(t, x) = \int_{(0, t) \times \mathbf{R}^d} \varphi(t - s, y - x) F(ds dy)$$

though with a little care since  $\varphi$  is in general a pseudo-measure



## A wave generalization

$$\partial_t^2 W = \mathcal{L}W + \dot{F}, \quad W(0) = 0, \quad \partial_t W(0+) = 0,$$
$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$  with  $d = 1, 2, 3$
- $\varphi$  = the fundamental solution for  $\partial_t^2 - \mathcal{L}$
- By solution we mean

$$W(t, x) = \int_{(0, t) \times \mathbf{R}^d} \varphi(t - s, y - x) F(ds dy)$$

though with a little care since  $\varphi$  is in general a pseudo-measure

- When does this make sense ( $\leftrightarrow$  the SPDE is well posed)?

## A wave generalization

$$\partial_t^2 W = \mathcal{L}W + \dot{F}, \quad W(0) = 0, \quad \partial_t W(0+) = 0,$$
$$\text{Cov}[\dot{F}(t, x), \dot{F}(s, y)] = \delta_0(t - s)\Gamma(x - y)$$

- $\mathcal{L}$  = generator of a Lévy process  $X = \{X_t\}_{t \geq 0}$  on  $\mathbf{R}^d$  with  $d = 1, 2, 3$
- $\varphi$  = the fundamental solution for  $\partial_t^2 - \mathcal{L}$
- By solution we mean

$$W(t, x) = \int_{(0, t) \times \mathbf{R}^d} \varphi(t - s, y - x) F(ds dy)$$

though with a little care since  $\varphi$  is in general a pseudo-measure

- When does this make sense ( $\leftrightarrow$  the SPDE is well posed)?
- When is the solution Hölder continuous?

## A harmless non-degeneracy condition

- We must assume from now on that  $X$  is *genuinely  $d$ -dimensional*; that is,

$$\psi^{-1}(0) = 0,$$

where  $E \exp(i\xi \cdot X_t) = \exp(-t\psi(\xi))$

## A harmless non-degeneracy condition

- We must assume from now on that  $X$  is *genuinely  $d$ -dimensional*; that is,

$$\psi^{-1}(0) = 0,$$

where  $E \exp(i\xi \cdot X_t) = \exp(-t\psi(\xi))$

- Lévy-Khintchine formula:

$$\psi(\xi) = -i\mathbf{a} \cdot \xi + \frac{1}{2}\xi \cdot \mathbf{A}\xi + \int_{\mathbb{R}^d} \left[ 1 - e^{iy \cdot \xi} + i(y \cdot \xi) \mathbf{1}_{B(0,1)}(y) \right] \nu(dy),$$

where  $\nu(F) =$  expected number of jumps of  $X$  in  $F$  by time 1

## A harmless non-degeneracy condition

- We must assume from now on that  $X$  is *genuinely  $d$ -dimensional*; that is,

$$\psi^{-1}(0) = 0,$$

where  $E \exp(i\xi \cdot X_t) = \exp(-t\psi(\xi))$

- Lévy-Khintchine formula:

$$\psi(\xi) = -i\mathbf{a} \cdot \xi + \frac{1}{2}\xi \cdot \mathbf{A}\xi + \int_{\mathbf{R}^d} \left[ 1 - e^{iy \cdot \xi} + i(y \cdot \xi) \mathbf{1}_{B(0,1)}(y) \right] \nu(dy),$$

where  $\nu(F)$  = expected number of jumps of  $X$  in  $F$  by time 1

- If  $\psi(\xi) = 0$  for some  $\xi \neq 0$ , then use

$$\operatorname{Re}\psi(\xi) = \frac{1}{2}\xi \cdot \mathbf{A}\xi + \int_{\mathbf{R}^d} [1 - \cos(y \cdot \xi)] \nu(dy),$$

to see that  $\mathbf{A}$  does not have full rank AND  $X$  can only have jumps with magnitude of form  $y$  where  $\xi \cdot y \in (2\pi\mathbf{Z})^d$ . Moreover,  $\mathbf{a} \perp \xi$

# On $H$ and $W$

Recall that

$$\begin{aligned}\partial_t H &= \mathcal{L}H + \dot{F}, & H(0) &= 0 \\ \partial_t^2 W &= \mathcal{L}W + \dot{F}, & W(0) = \partial_t W(0+) &= 0, & d &= 1, 2, 3\end{aligned}$$

Theorem (Brzézniak-van Neerven, 2003; K-Kim, 2015)

*Assume that  $X$  is genuinely  $d$ -dimensional. Then,  $H$  and/or  $W$  are well-defined random fields if and only if*

$$\int_{\mathbb{R}^d} \frac{\hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty.$$

$2\operatorname{Re}\psi$  = characteristic exponent of  $X - X'$  [replica symmetry]

# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

Theorem (K–Sanz–Solé, 2022)



# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

## Theorem (K–Sanz-Solé, 2022)

- $H$  and/or  $W$  are Hölder continuous in  $t$  for every  $x$  if and only if

$$\int_{\mathbb{R}^d} \frac{|\psi(\xi)|^a \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } a \in (0, 1);$$

# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

## Theorem (K–Sanz–Solé, 2022)

- $H$  and/or  $W$  are Hölder continuous in  $t$  for every  $x$  if and only if

$$\int_{\mathbb{R}^d} \frac{|\psi(\xi)|^a \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } a \in (0, 1);$$

- $H$  and/or  $W$  are Hölder continuous in  $x$  for one – hence every –  $t > 0$  iff

$$\int_{\mathbb{R}^d} \frac{\|\xi\|^{2b} \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } b \in (0, 1)$$

# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

## Theorem (K–Sanz–Solé, 2022)

- $H$  and/or  $W$  are Hölder continuous in  $t$  for every  $x$  if and only if

$$\int_{\mathbb{R}^d} \frac{|\psi(\xi)|^a \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } a \in (0, 1);$$

- $H$  and/or  $W$  are Hölder continuous in  $x$  for one – hence every –  $t > 0$  iff

$$\int_{\mathbb{R}^d} \frac{\|\xi\|^{2b} \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } b \in (0, 1)$$

- Fact (Bochner, 30's):  $|\psi(\xi)| \lesssim 1 + \|\xi\|^2$

# On $H$ and $W$

- Assume  $X$  is genuinely  $d$ -dimensional

## Theorem (K–Sanz-Solé, 2022)

- $H$  and/or  $W$  are Hölder continuous in  $t$  for every  $x$  if and only if

$$\int_{\mathbb{R}^d} \frac{|\psi(\xi)|^a \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } a \in (0, 1);$$

- $H$  and/or  $W$  are Hölder continuous in  $x$  for one – hence every –  $t > 0$  iff

$$\int_{\mathbb{R}^d} \frac{\|\xi\|^{2b} \hat{\Gamma}(d\xi)}{1 + \operatorname{Re}\psi(\xi)} < \infty \quad \text{for some } b \in (0, 1)$$

- Fact (Bochner, 30's):  $|\psi(\xi)| \lesssim 1 + \|\xi\|^2$
- These NASCs remain valid for nonlinear SPDEs with additive noise

# Continuity

- Standard method: A Kolmogorov-type continuity condition; e.g.,

# Continuity

- Standard method: A Kolmogorov-type continuity condition; e.g.,

Theorem (Slutsky, 1937; Lévy, 1948; Čencov, 1956; Dudley, 1967; Garsia-Rodemich-Rumsey, 1970; ...)

If  $\{X_t\}_{t \in T}$  is a real-valued stochastic process and  $T \subset \mathbf{R}^N$  is compact, and if there exist  $\alpha_1, \dots, \alpha_N \in (0, 1]$  and  $k > \sum_{j=1}^N \alpha_j^{-1}$  such that

$$\|X_t - X_s\|_{L^k(\Omega)} \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j} \quad \text{uniformly for all } s, t \in T,$$

then  $X$  is continuous a.s. In fact, with probability one,

$$|X_t - X_s| \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j q} \text{ for every } q \in (0, 1 - k^{-1} \sum_{j=1}^N \alpha_j^{-1}).$$

# Continuity

- Standard method: A Kolmogorov-type continuity condition; e.g.,

Theorem (Slutsky, 1937; Lévy, 1948; Čencov, 1956; Dudley, 1967; Garsia-Rodemich-Rumsey, 1970; ...)

If  $\{X_t\}_{t \in T}$  is a real-valued stochastic process and  $T \subset \mathbf{R}^N$  is compact, and if there exist  $\alpha_1, \dots, \alpha_N \in (0, 1]$  and  $k > \sum_{j=1}^N \alpha_j^{-1}$  such that

$$\|X_t - X_s\|_{L^k(\Omega)} \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j} \quad \text{uniformly for all } s, t \in T,$$

then  $X$  is continuous a.s. In fact, with probability one,

$$|X_t - X_s| \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j q} \quad \text{for every } q \in (0, 1 - k^{-1} \sum_{j=1}^N \alpha_j^{-1}).$$

- This is optimal (Hahn-Klass, 1977; Kôno, 1978; Ibragimov, 1979)

# Continuity

- Standard method: A Kolmogorov-type continuity condition; e.g.,

Theorem (Slutsky, 1937; Lévy, 1948; Čencov, 1956; Dudley, 1967; Garsia-Rodemich-Rumsey, 1970; ...)

If  $\{X_t\}_{t \in T}$  is a real-valued stochastic process and  $T \subset \mathbf{R}^N$  is compact, and if there exist  $\alpha_1, \dots, \alpha_N \in (0, 1]$  and  $k > \sum_{j=1}^N \alpha_j^{-1}$  such that

$$\|X_t - X_s\|_{L^k(\Omega)} \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j} \quad \text{uniformly for all } s, t \in T,$$

then  $X$  is continuous a.s. In fact, with probability one,

$$|X_t - X_s| \lesssim \sum_{j=1}^N |t_j - s_j|^{\alpha_j q} \text{ for every } q \in (0, 1 - k^{-1} \sum_{j=1}^N \alpha_j^{-1}).$$

- This is optimal (Hahn-Klass, 1977; Kôno, 1978; Ibragimov, 1979)
- Needs a slight adjustment since optimal  $\alpha_j$ 's aren't so easy to find



# Continuity: Part I

- I will describe the slight adjustment for one-parameter processes, since that is all that one ultimately needs

# Continuity: Part I

- I will describe the slight adjustment for one-parameter processes, since that is all that one ultimately needs
- Let  $X = \{X_t\}_{t \in [0,1]}$  be a real-valued stochastic process and write

$$g(r) = \sup_{\substack{s, t \in [0,1] \\ |s-t| \leq r}} \|X_t - X_s\|_{L^k(\Omega)},$$

and suppose  $g$  is finite everywhere.

# Continuity: Part I

- I will describe the slight adjustment for one-parameter processes, since that is all that one ultimately needs
- Let  $X = \{X_t\}_{t \in [0,1]}$  be a real-valued stochastic process and write

$$g(r) = \sup_{\substack{s, t \in [0,1] \\ |s-t| \leq r}} \|X_t - X_s\|_{L^k(\Omega)},$$

and suppose  $g$  is finite everywhere.

## Lemma

*If  $\int_0^1 r^{-1-a} g(r) dr < \infty$  for some  $a \in (0, 1)$ , then  $g(r) \lesssim r^a$ .*

# Proof

The proof is short and abelian/tauberian (fractal?):

- $\int_0^1 g(r) \frac{dr}{r^{1+a}} < \infty \Leftrightarrow \sum_{n=0}^{\infty} e^{na} g(e^n) < \infty \Rightarrow \lim_{n \rightarrow \infty} e^{na} g(e^{-n}) = 0$

# Proof

The proof is short and abelian/tauberian (fractal?):

- $\int_0^1 g(r) \frac{dr}{r^{1+a}} < \infty \Leftrightarrow \sum_{n=0}^{\infty} e^{na} g(e^n) < \infty \Rightarrow \lim_{n \rightarrow \infty} e^{na} g(e^{-n}) = 0$
- If  $s \in (e^{-n-1}, e^{-n}]$  then

$$\frac{g(s)}{s^a} \leq e^{(n+1)a} g(e^{-n}) \lesssim 1. \quad \square$$

# Proof

The proof is short and abelian/tauberian (fractal?):

- $\int_0^1 g(r) \frac{dr}{r^{1+a}} < \infty \Leftrightarrow \sum_{n=0}^{\infty} e^{na} g(e^n) < \infty \Rightarrow \lim_{n \rightarrow \infty} e^{na} g(e^{-n}) = 0$
- If  $s \in (e^{-n-1}, e^{-n}]$  then

$$\frac{g(s)}{s^a} \leq e^{(n+1)a} g(e^{-n}) \lesssim 1. \quad \square$$

## Corollary

If

$$\int_0^1 \sup_{\substack{s, t \in [0, 1] \\ |s-t| \leq r}} \|X_t - X_s\|_{L^k(\Omega)} \frac{dr}{r^{1+a}} < \infty \quad \text{for some } a \in (1/k, 1),$$

then  $X$  is Hölder continuous.

## Continuity: Part II

- For a converse we will need the following.

## Continuity: Part II

- For a converse we will need the following.

### Lemma

*If  $f : (0, 1) \rightarrow \mathbf{R}_+$  is measurable and  $\int_0^1 r^{-1-a} f(r) dr = \infty$  for some  $a \in (0, 1)$ , then  $\limsup_{r \rightarrow 0^+} r^{-b} f(r) = \infty$  for every  $b > a$ .*



## Continuity: Part II

- For a converse we will need the following.

### Lemma

If  $f : (0, 1) \rightarrow \mathbf{R}_+$  is measurable and  $\int_0^1 r^{-1-a} f(r) dr = \infty$  for some  $a \in (0, 1)$ , then  $\limsup_{r \rightarrow 0^+} r^{-b} f(r) = \infty$  for every  $b > a$ .

- **Proof.**

## Continuity: Part II

- For a converse we will need the following.

### Lemma

If  $f : (0, 1) \rightarrow \mathbf{R}_+$  is measurable and  $\int_0^1 r^{-1-a} f(r) dr = \infty$  for some  $a \in (0, 1)$ , then  $\limsup_{r \rightarrow 0+} r^{-b} f(r) = \infty$  for every  $b > a$ .

- **Proof.**

- 1 WLOG  $f$  is increasing; else replace  $f(r)$  by  $\sup_{s \in (0, r)} f(s)$

## Continuity: Part II

- For a converse we will need the following.

### Lemma

If  $f : (0, 1) \rightarrow \mathbf{R}_+$  is measurable and  $\int_0^1 r^{-1-a} f(r) dr = \infty$  for some  $a \in (0, 1)$ , then  $\limsup_{r \rightarrow 0^+} r^{-b} f(r) = \infty$  for every  $b > a$ .

- **Proof.**

- 1 WLOG  $f$  is increasing; else replace  $f(r)$  by  $\sup_{s \in (0, r)} f(s)$
- 2 Reverse the previous proof:

$$\int_0^1 f(r) \frac{dr}{r^{1+a}} = \infty \Leftrightarrow \sum_{n=0}^{\infty} e^{na} f(e^{-na}) = \infty \Rightarrow f(e^{-na}) \geq e^{-nb},$$

for infinitely many values of  $n$ ; for otherwise,

$$\sum_{n=0}^{\infty} e^{na} f(e^{-n}) \leq \sum_{n=0}^{\infty} e^{n(a-b)} < \infty. \quad \square$$

## Continuity: Part II

- This yields the following.

## Continuity: Part II

- This yields the following.

### Lemma

If

$$\iint_{(0,1)^2} \|X_t - X_s\|_{L^k(\Omega)} \frac{dt ds}{|t - s|^{1+a}} = \infty$$

for some  $a \in (0, 1)$ , then  $\limsup_{s \rightarrow t} |t - s|^{-b} \|X_t - X_s\|_{L^k(\Omega)} > 0$  if  $b > a$ .

## Continuity: Part II

- This yields the following.

### Lemma

If

$$\iint_{(0,1)^2} \|X_t - X_s\|_{L^k(\Omega)} \frac{dt ds}{|t - s|^{1+a}} = \infty$$

for some  $a \in (0, 1)$ , then  $\limsup_{s \rightarrow t} |t - s|^{-b} \|X_t - X_s\|_{L^k(\Omega)} > 0$  if  $b > a$ .

- Finally, by the Paley-Zygmund inequality (1932),

$$P \left\{ |X_t - X_s| \geq \frac{1}{2} \|X_t - X_s\|_{L^1(\Omega)} \right\} \geq \frac{\|X_t - X_s\|_{L^1(\Omega)}^2}{4 \|X_t - X_s\|_{L^2(\Omega)}^2}$$

## Continuity: Part II

- This yields the following.

### Lemma

If

$$\iint_{(0,1)^2} \|X_t - X_s\|_{L^k(\Omega)} \frac{dt ds}{|t - s|^{1+a}} = \infty$$

for some  $a \in (0, 1)$ , then  $\limsup_{s \rightarrow t} |t - s|^{-b} \|X_t - X_s\|_{L^k(\Omega)} > 0$  if  $b > a$ .

- Finally, by the Paley-Zygmund inequality (1932),

$$\mathbb{P} \left\{ |X_t - X_s| \geq \frac{1}{2} \|X_t - X_s\|_{L^1(\Omega)} \right\} \geq \frac{\|X_t - X_s\|_{L^1(\Omega)}^2}{4 \|X_t - X_s\|_{L^2(\Omega)}^2}$$

- If  $X$  is Gaussian then the right-hand side =  $(2\pi)^{-1}$ ;

## Continuity: Part II

- This yields the following.

### Lemma

If

$$\iint_{(0,1)^2} \|X_t - X_s\|_{L^k(\Omega)} \frac{dt ds}{|t - s|^{1+a}} = \infty$$

for some  $a \in (0, 1)$ , then  $\limsup_{s \rightarrow t} |t - s|^{-b} \|X_t - X_s\|_{L^k(\Omega)} > 0$  if  $b > a$ .

- Finally, by the Paley-Zygmund inequality (1932),

$$P \left\{ |X_t - X_s| \geq \frac{1}{2} \|X_t - X_s\|_{L^1(\Omega)} \right\} \geq \frac{\|X_t - X_s\|_{L^1(\Omega)}^2}{4 \|X_t - X_s\|_{L^2(\Omega)}^2}$$

- If  $X$  is Gaussian then the right-hand side =  $(2\pi)^{-1}$ ;
- If  $X$  is Gaussian then  $\|X_t - X_s\|_{L^1(\Omega)} = C_k \|X_t - X_s\|_{L^k(\Omega)}$ ;



## Continuity: Part II

- This yields the following.

### Lemma

If

$$\iint_{(0,1)^2} \|X_t - X_s\|_{L^k(\Omega)} \frac{dt ds}{|t - s|^{1+a}} = \infty$$

for some  $a \in (0, 1)$ , then  $\limsup_{s \rightarrow t} |t - s|^{-b} \|X_t - X_s\|_{L^k(\Omega)} > 0$  if  $b > a$ .

- Finally, by the Paley-Zygmund inequality (1932),

$$P \left\{ |X_t - X_s| \geq \frac{1}{2} \|X_t - X_s\|_{L^1(\Omega)} \right\} \geq \frac{\|X_t - X_s\|_{L^1(\Omega)}^2}{4 \|X_t - X_s\|_{L^2(\Omega)}^2}$$

- If  $X$  is Gaussian then the right-hand side =  $(2\pi)^{-1}$ ;
- If  $X$  is Gaussian then  $\|X_t - X_s\|_{L^1(\Omega)} = C_k \|X_t - X_s\|_{L^k(\Omega)}$ ;
- If  $X$  is Gaussian then it has good 0-1 laws (Kallianpur, 1970; Cambanis-Rajput, 1973).