THE UNIVERSITY OF ALABAMA IN HUNTSVILLE

## MECHANICS OF MATERIALS: NORMAL \& SHEAR STRESS

## Normal Stress Caused by Bending:

- Recall shear and moment calculation and graphing techniques:

$$
\begin{gathered}
M=\int V d x=\iint w d x \\
w=\frac{d}{d x} w=\frac{d^{2}}{d x^{2}} M
\end{gathered}
$$



| Load (w) | Shear (V) | Moment <br> $\mathbf{( M )}$ |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| $-w$ (constant) | $w x$ (linear) | $w x^{2}$ <br> (parabolic) |
| $-w x$ (linear) | $w x^{2}$ (parabolic) | $w x^{3}$ |
| $-w x^{2}$ (parabolic) | $w x^{3}$ | $w x^{4}$ |

- The Neutral Axis is the axis at which a member in bending experiences no normal stress:

- When bending, we observe how stress varies as a point moves away from the Neutral Axis.

$$
\begin{gathered}
\varepsilon=-\frac{y}{c} \cdot \varepsilon_{\max } \text { such that } \sigma_{x}=E\left(-\frac{y}{c}\right) \cdot \varepsilon_{\max } \text { and } \sigma_{x}=-\frac{y}{c} \cdot \sigma_{\max } \\
I=\int y^{2} d A=\frac{M c}{\sigma_{\max }} \text { or } \sigma_{x}=-\frac{M y}{I} \text { for any } y \begin{array}{c}
\text { The negative sign is necessary } \\
\begin{array}{c}
\text { because for a positive } y \text { point, the } \\
\text { beam experiences compression }
\end{array}
\end{array}
\end{gathered}
$$

- The Parallel Axis Theorem is often used for objects that are not strictly rectangular or circular, but rather are comprised of several shapes:

$$
I_{i}=I^{\prime}+A_{i} d_{i}^{2}
$$

| Rectangle | $I_{\text {rectangle }}=\frac{1}{12} b h^{3}$ |
| :---: | :---: |
| Circle | $I_{\text {circle }}=\frac{1}{4} \pi R^{4}$ |
| Triangle | $I_{\text {triangle }}=\frac{1}{36} b h^{3}$ |
| Semi-circle | $I_{\text {semicircle }}=\frac{1}{8} \pi R^{4}$ |

$b$ is in the direction parallel (II) to the NA $h$ is in the direction perpendicular $(\perp)$ to the NA

- Unsymmetrical bending due to moments at angles requires the moment vector be decomposed:



## Shear Stress Caused By Shear Force:

- There are two directions in which shear force acts: longitudinal (along the length of the beam) and transverse (on cut plane)

1. Horizontal shear (longitudinal): $\Delta H=\frac{V Q}{I} \Delta x$
2. Transverse shear: $\tau_{a v g}=\frac{V Q}{I t}$ and $\tau_{\max }=1.5 \cdot \frac{V_{\max }}{A}$

- $\quad$ Shear flow (shear force per unit length): $q=\frac{\Delta H}{\Delta x}=\frac{V Q}{I}$


| $\bar{y}$ | Distance from NA to the <br> centroid of A |
| :---: | :---: |
| $A$ | Area above the point or above <br> the Shear Plane (opposite side <br> of NA) |
| $I$ | Moment of inertia of entire <br> object (independent of $A$ or $\bar{y}$ ) |
| $V$ | Transverse force applied |
| $t$ | Thickness of the object at the <br> point observed or Shear Plane |

